CONEX-AGAP

Agilis-D Controller
with Strain Gages Feedback

Applet Manual

V2.0.0

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Experience | Solutions

For Motion, Think Newport™

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CONEX-AGAP
Agilis-D Controller with Strain Gages Feedback

1.0   Introduction

1.1   Purpose

The purpose of this document is to provide instructions on how to use the Newport CONEX-AGAP Applet.

1.2   Overview

The Newport CONEX-AGAP Applet is a software application that has a graphical user interface (GUI) which allows the user to interact with the CONEX-AGAP controller with strain gages feedback.

1.3   Controller State Diagram

The CONEX-AGAP controller is defined by the following state diagram.
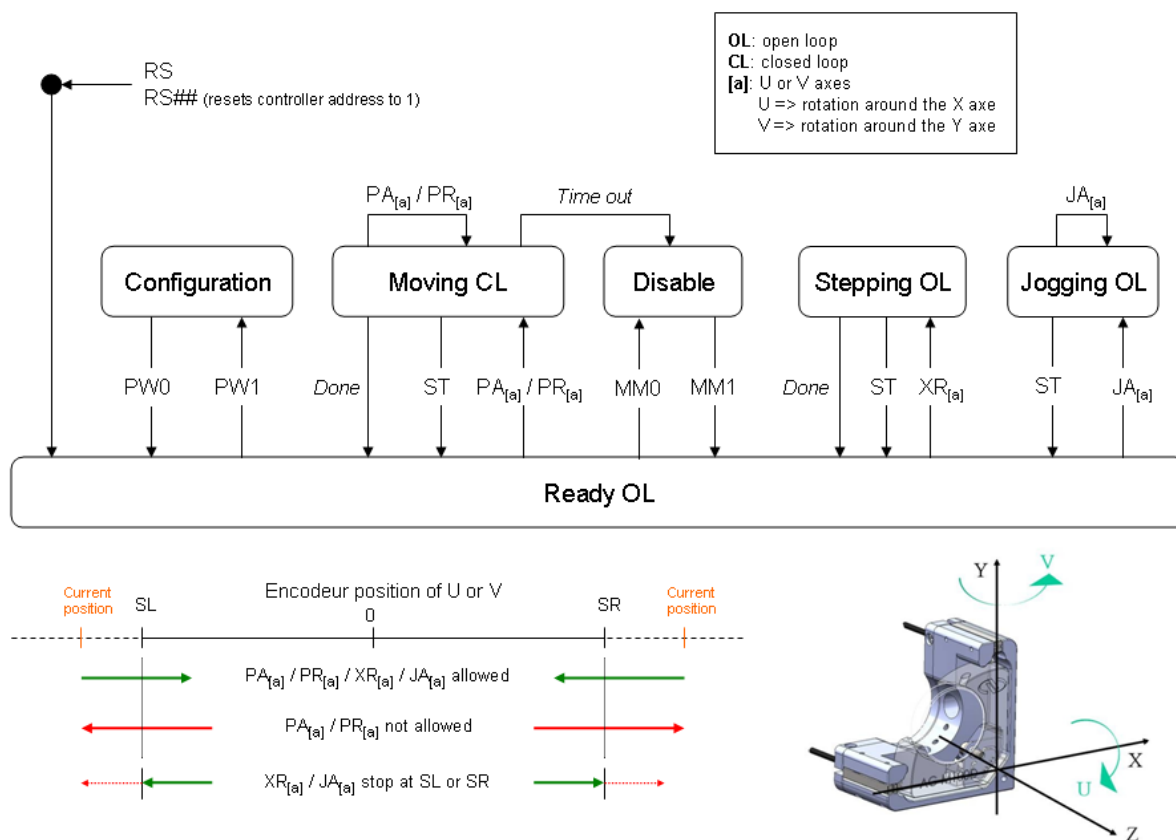
Controller's LED display:

CONFIGURATION: SLOW BLINKING RED.

READY OL: SOLID GREEN.

DISABLE: SLOW BLINKING GREEN.

MOVING CL: FAST BLINKING GREEN.

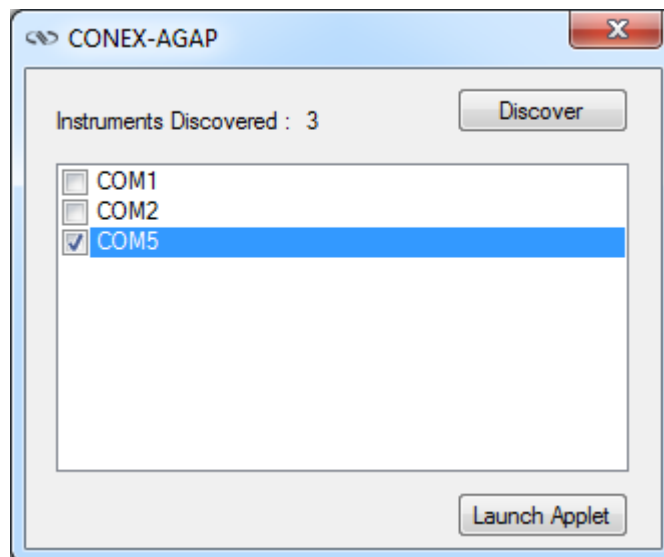STEPPING OL: FAST BLINKING GREEN.

JOGGING OL: FAST BLINKING GREEN.

2.0   User Interface

2.1   Device selection

Click on the "Discover" button to get a list of detected serial COM ports.

Next, select the serial COM port that corresponds to your device and click the "Launch Applet" button to run the graphical interface.

2.2   Configuration

The Configuration tab allows the user to view and / or change information related to the logging configuration and the instrument settings. Read only values are displayed for the log file name and the log file path. The logging level may be changed to any of the settings in the drop-down list on the right hand side. Trace is the most detailed of the settings and when this setting is selected the applet logs everything. Critical Error is the least detailed of the settings and when this setting is selected the applet will only log errors that are defined to be critical.
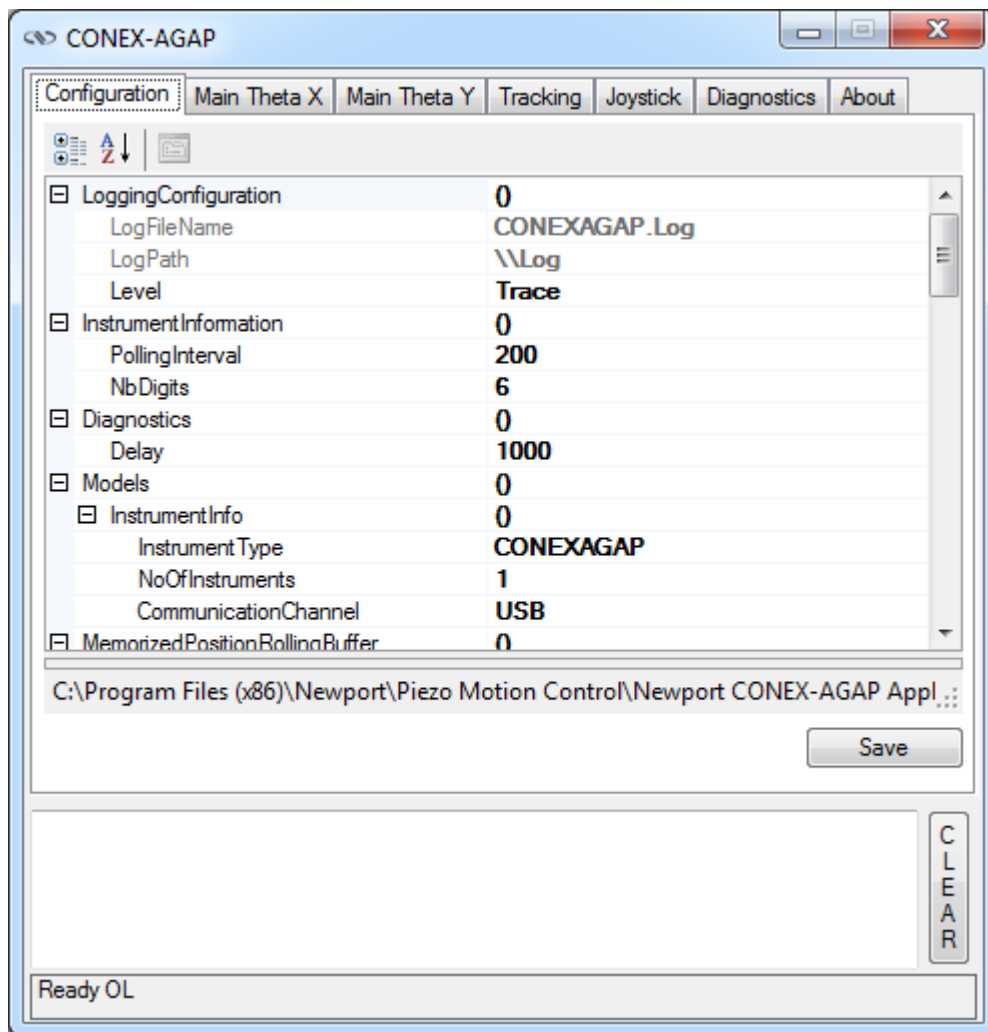
The polling interval defines the number of milliseconds between each time the applet polls the controller for the latest information. The user may change the polling interval by entering a value.

The **Save** button allows to save the current settings to the configuration file.

Configurable settings

The following table describes all the settings that can be change by the user.

Parameter	Description	Values	Default
LoggingConfiguration			
Level	Logging level. Trace is the most detailed of the settings and when this setting is selected the applet logs everything. Critical Error is the least detailed of the settings and when this setting is selected the applet will only log errors that are defined to be critical.	Trace Detail Equipment Message Info Warning Error Critical Errror	**Trace**
Permission	Access permission	A HexBinary	
InstrumentInformation			
PollingInterval	The polling interval defines the number of milliseconds between each time the applet polls the instrument for the latest information.	An Integer	**500**
NbDigits	Number of fractional digits after the decimal point.	An Integer	**6**
Models\InstrumentInfo			
CommunicationChannel	The communication channel	USB	**USB**
MemorizedPosition			
MaxItem	MaxItem defines the maximum number of memorized positions by the applet.		**5**
Positions	The list of the memorized position. The format is "Name of position #1;X position #1;Y position #1;Name of position #2;X position #2;Y position #2…"		
TrackingConfiguration			
XDirection	The axis direction for X axis.	Normal Inverse	**Normal**
YDirection	The axis direction for Y axis.	Normal Inverse	**Normal**
StartedSensibility	The started sensibility defines the zoom level of the tracking panel after applet launching.	An Integer (1<20)	**4**
MinimumAmplitudeX	The minimum amplitude for X axis.	A Double	**0.001**
MaximumAmplitudeX	The maximum amplitude for X axis.	A Double	**20**
MinimumAmplitudeY	The minimum amplitude for Y axis.	A Double	**0.001**
MaximumAmplitudeY	The maximum amplitude for Y axis.	A Double	**20**
IncrementalStep	The maximum incremental step when the tracking is in incremental displacement mode.	A Double	**0.05**
Orientation	The mouse orientation: Horizontal = X and Vertical = Y (Normal) Horizontal = Y and Vertical = X (Inverse)	Normal Inverse	**Normal**
MouseConfiguration			
EnterPositionTracking	Activate the tracking mode.	MouseButton/MouseEvent*	**Middle/Click**
ExitPositionTracking	Desactivate the tracking mode.	MouseButton/MouseEvent*	**Middle/Click**
SelectXaxis	Select/Unselect X axis.	MouseButton/MouseEvent*	**Left/Click**
SelectYaxis	Select/Unselect Y axis.	MouseButton/MouseEvent*	**Right/Click**
IncreaseSensibility	Increase the zoom level of the tracking panel.	MouseButton/MouseEvent*	**Middle/Wheel up**
DecreaseSensibility	Decrease the zoom level of the tracking panel.	MouseButton/MouseEvent*	**Middle/Wheel down**
MemorizeCurrentPosition	Save the current positions.	MouseButton/MouseEvent*	**Left/Double-Click**

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This table describes mouse parameters for the MouseConfiguration section.

| *MouseButton/MouseEvent			
	The mouse parameters for triggering the action		
MouseButton	The selected mouse button.	None Left Right Middle XButton1 Xbutton2	
MouseEvent	The event mouse on the selected mouse button.	None Click Double-Click Wheel Down Wheel Up Down Up	

2.3   Main

The Main tab displays the main controls in the applet like a virtual front panel. It is updated each time the polling interval timer expires.

One Main tab by axis:
1. Main Theta X
2. Main Theta Y
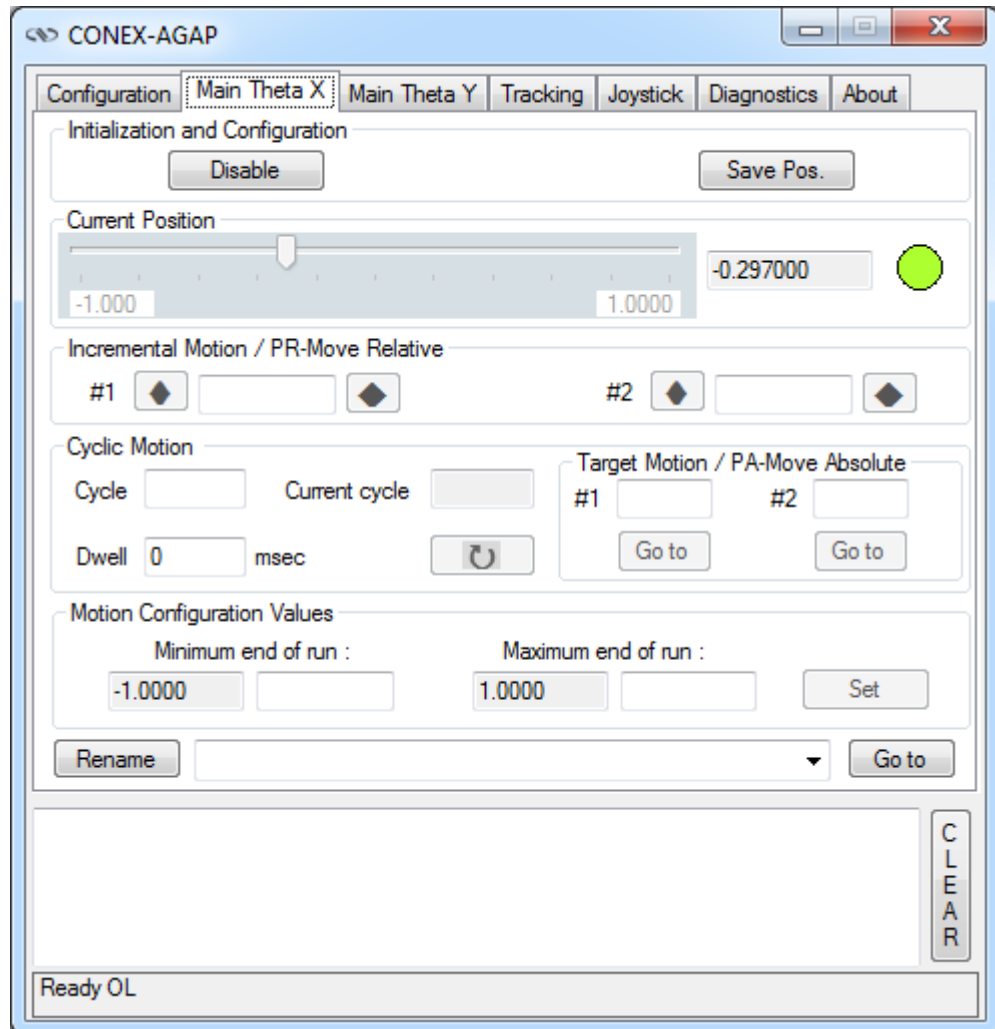
"Initialization and Configuration"

In the "Initialization and Configuration" area, the first button allows to execute the next enable command to change the controller status. To see the different controller states, refer to the controller state diagram. The second button "Save Pos." allows memorizing the current positions (Theta X and Theta Y) in the combo box. As soon as a new position is memorized, this is displayed in the trace.

"Current Position"

In the "Current Position" area, the current position Theta X (or Theta Y) is displayed in a text box and visualize in a slider. The slider limits are defined with the ends of run. A led shows the current controller state. When you move the mouse over the led, the controller state is displayed in an information balloon.

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"Incremental Motion / PR-Move Relative"

In the "Incremental Motion / PR-Move Relative" area, two steps can be defined. For each step, a relative move can be performing in the negative direction or a positive direction.

"Cyclic Motion" and "Target position / PA-Move Absolute"

In the "Cyclic Motion" area, a motion cycle is configured with a number of cycles (Cycle) and a temporization time in milliseconds (dwell). The motion cycle gets the defined target positions from the "Target position / PA-Move Absolute' area to perform the cycle.
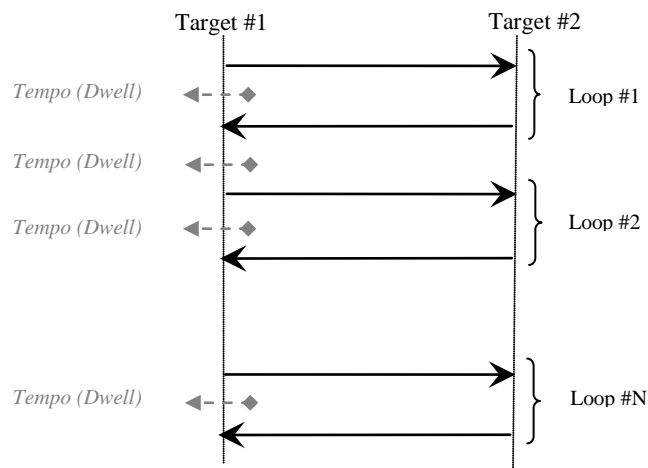
In the "Target position / PA-Move Absolute" area, two target positions can be defined. The "Go to" button allows executing the absolute move to go to the specified target position.

"Motion Configuration Values"

In the "Motion Configuration Values", the current ends of run are displayed in a disabled text box: "Minimum end of run" and "Maximum end of run". These ends of run can be modified and saved with the "Set" button.

Memorized positions

The combo box allows memorizing the positions get by the "Save Pos." button. Each of these positions can be renamed or deleted. To execute an absolute move to go to one of these memorized positions, select one item of the combo box and click on "Go to" button. When the mouse moves over to the combo box, the positions of the selected memorized position are showed in an information balloon.

Rename a memorized position: Select an item of the combo box, edit the position name to change it and click on the "Rename" button to save the new position name.
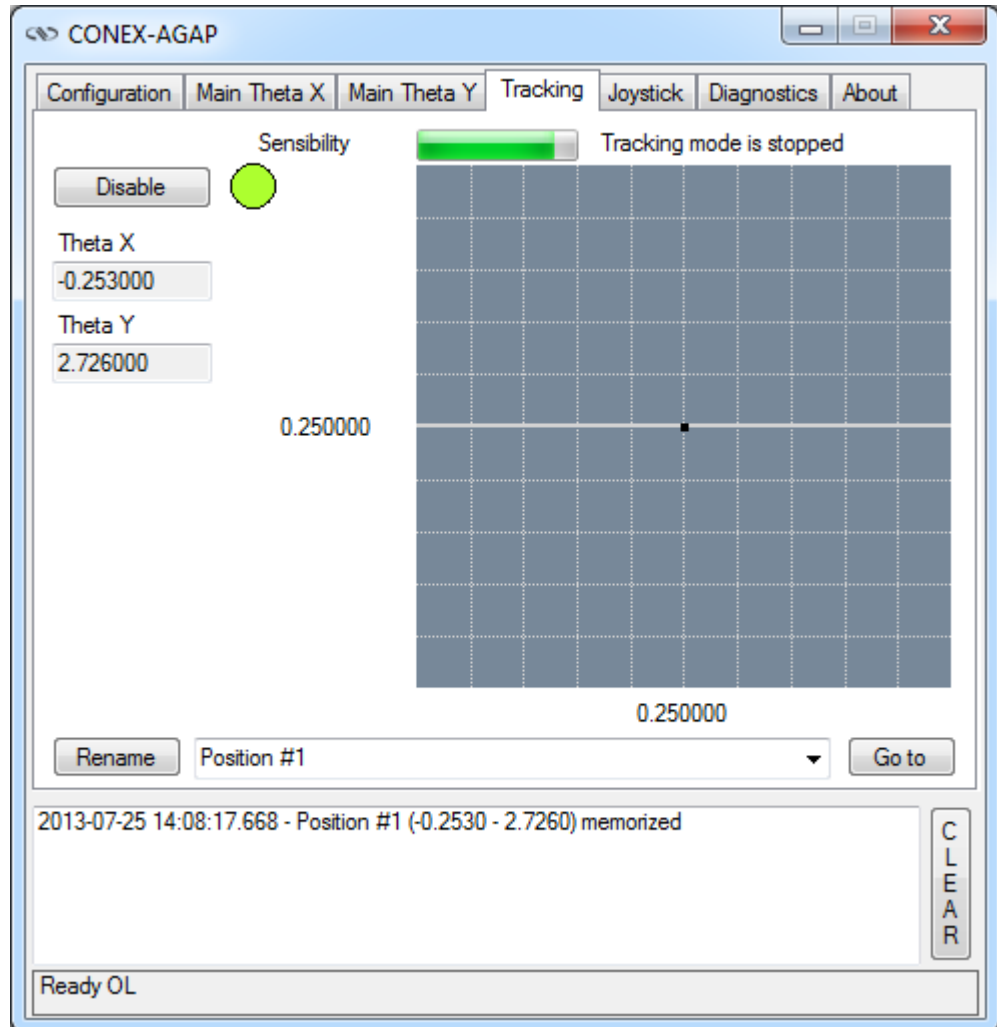
Delete a memorized position: Select an item of the combo box, click right on the mouse and select the "Delete" menu to delete the selected memorized position.

2.4   Tracking

The Tracking tab allows entering in the position tracking mode. The tracking position mode uses the mouse.

NOTE

In the tracking mode, the cursor is confined in the tracking position area.

The button allows executing the next enable command to change the controller status. Its name changes in relation to the controller state. To see the different controller states, refer to the controller state diagram.

A led shows the current controller state. When you move the mouse over the led, the controller state is displayed inside an information balloon.

Two text box allow displaying the current positions (Theta X and Theta Y)

The combo box allows memorizing the positions with a mouse double-click. Each of these positions can be renamed or deleted. To execute an absolute move to go to one of these memorized positions, select one item of the combo box and click on "Go to" button. When the mouse moves over to the combo box, the positions of the selected memorized position are showed in an information balloon.

Rename a memorized position: Select an item of the combo box, edit the position name to change it. Click on the "Rename" button to save the new position name.

Delete a memorized position: Select an item of the combo box, click right on the mouse and select the "Delete" menu to delete the selected memorized position.

Tracking panel and mouse

The current position is represented by a black spot.

The amplitudes (Theta X and Theta Y) are defined with the ends of run.

First click (middle mouse button) allows entering in the tracking mode and the mouse cursor position is attached to the current position. As soon as the tracking mode is activated, the cursor is represented by a **hand** 🖐 and the CONEX-AGAP goes to the TRACKING state. Next, each mouse move generates a displacement command. The second click (middle mouse button) exits the tracking mode.

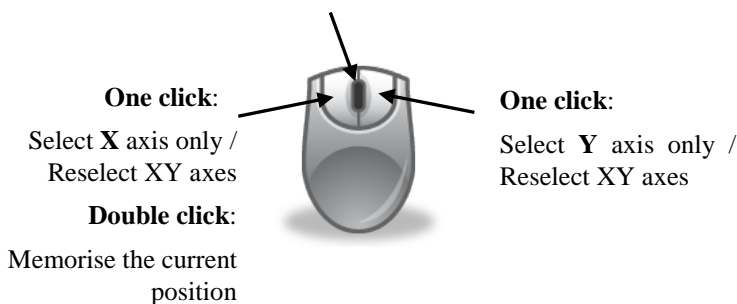The wheel button allows increasing or decreasing the sensibility.

A right double-click allows memorizing the current positions (Theta X and Theta Y) in the combo box. Each new memorized position is displayed in the trace.

Default mouse configuration:

One click: Enter / Exit the tracking position mode.
Roll up: increase zoom factor
Roll down: decrease zoom factor

One click:

Select **X** axis only /
Reselect XY axes

Double click:

Memorise the current
position

One click:

Select **Y** axis only /
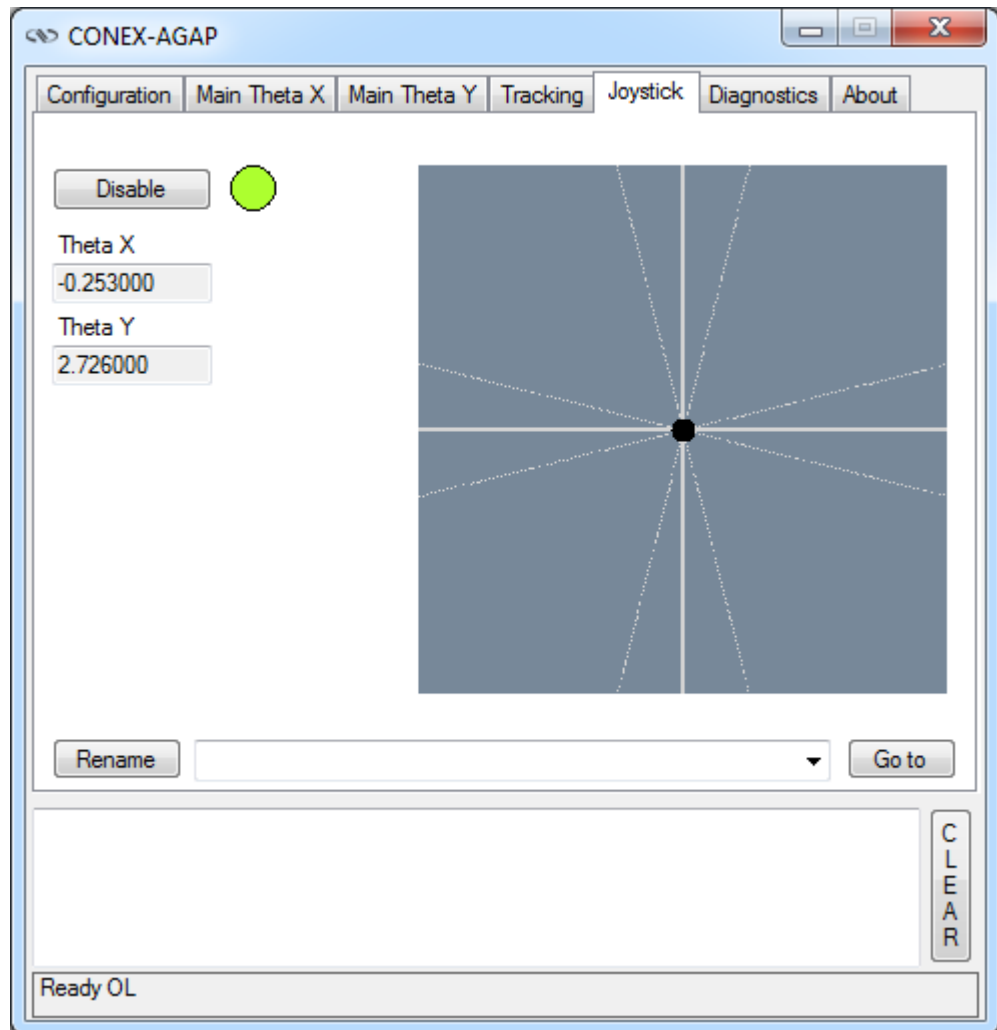Reselect XY axes

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NOTE

The mouse configuration can be modified in the "Configuration" tab.

2.5   Joystick

The Joystick tab allows entering in the velocity tracking mode (Joystick mode). The joystick mode uses the mouse.

NOTE

In the joystick mode, the cursor is confined in the joystick position area.

The button allows executing the next enable command to change the controller status. Its name changes in relation to the controller state. To see the different controller states, refer to the controller state diagram.

A led shows the current controller state. When you move the mouse over the led, the controller state is displayed inside an information balloon.

Two text box allow displaying the current positions (Theta X and Theta Y)

The combo box allows memorizing the positions with a mouse double-click. Each of these positions can be renamed or deleted. To execute an absolute move to go to one of these memorized positions, select one item of the combo box and click on "Go to" button. When the mouse moves over to the combo box, the positions of the selected memorized position are showed in an information balloon.

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Rename a memorized position: Select an item of the combo box, edit the position name to change it and click on the "Rename" button to save the new position name.
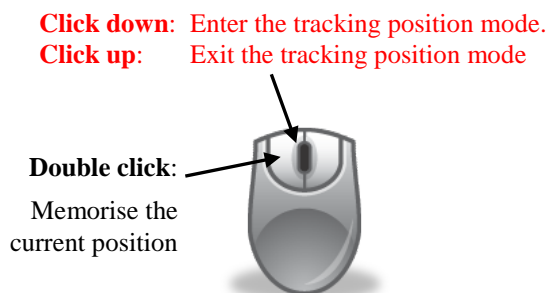
Delete a memorized position: Select an item of the combo box, click right on the mouse and select the "Delete" menu to delete the selected memorized position.

Joystick panel and mouse

Click down (middle mouse button by default) to enter in the joystick mode and the mouse cursor is attached to the joystick cursor. As soon as the joystick mode is activated, the cursor is represented by a **hand** 🖑 and the CONEX-AGAP goes to the JOGGING state. Next, with the button down, each mouse move generates a jog command. The click up (middle mouse button) exits the tracking mode.

A left double-click allows memorizing the current positions (Theta X and Theta Y) in the combo box. Each new memorized position is displayed in the trace.

Default mouse configuration:

Click down: Enter the tracking position mode.
Click up: Exit the tracking position mode

Double click:

Memorise the
current position

NOTE

The mouse configuration can be modified in the "Configuration" tab.

2.6   Diagnostics

The Diagnostics tab allows the user to enter instrument commands and to view the history of commands sent and responses received. This list of commands and the syntax of each command can be found in the user's manual for the instrument.

The Send button is used to send the contents of the Command text box to the instrument.

A file of commands can be sent line by line to the instrument with the "Send Command file" button.
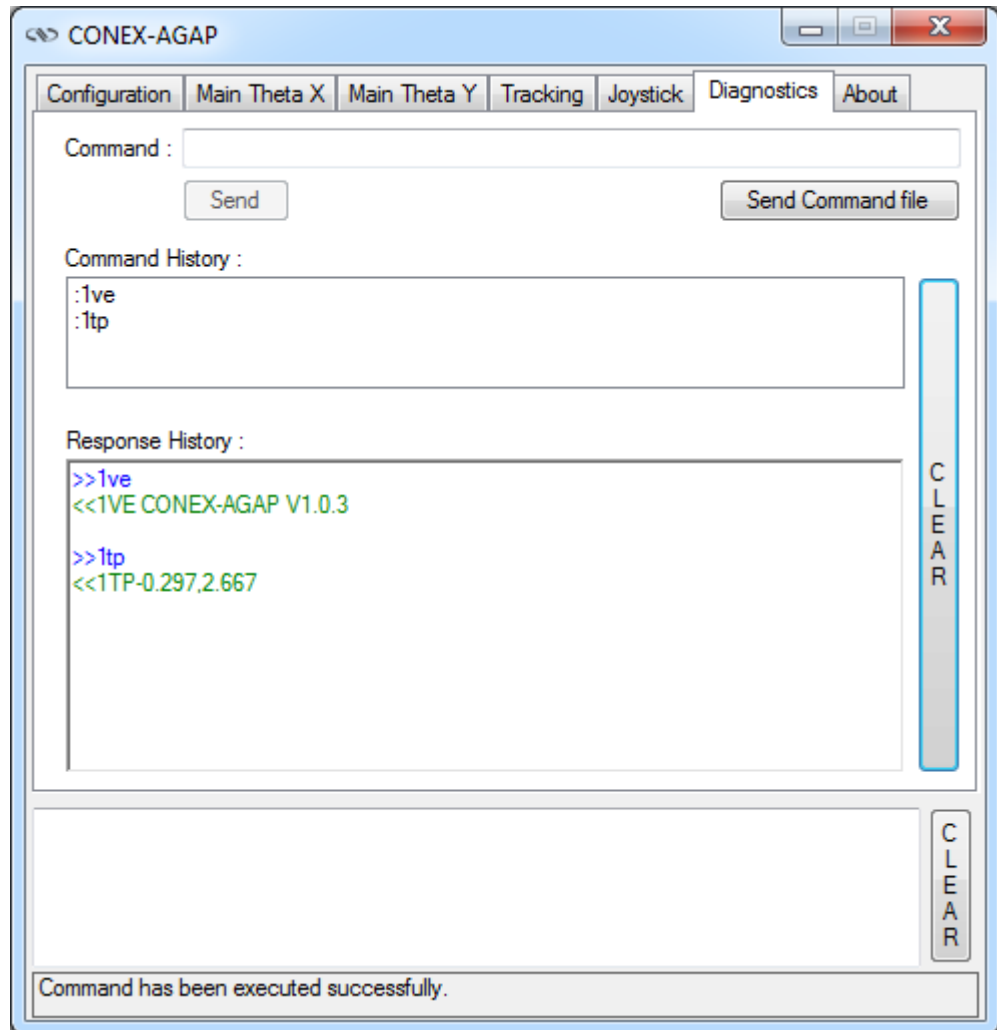
2.7   About

The About tab allows to display information about the applet and the connected instrument. It displays the applet name, version, and copyright information. It also displays the instrument model, instrument key (serial number) and firmware version.
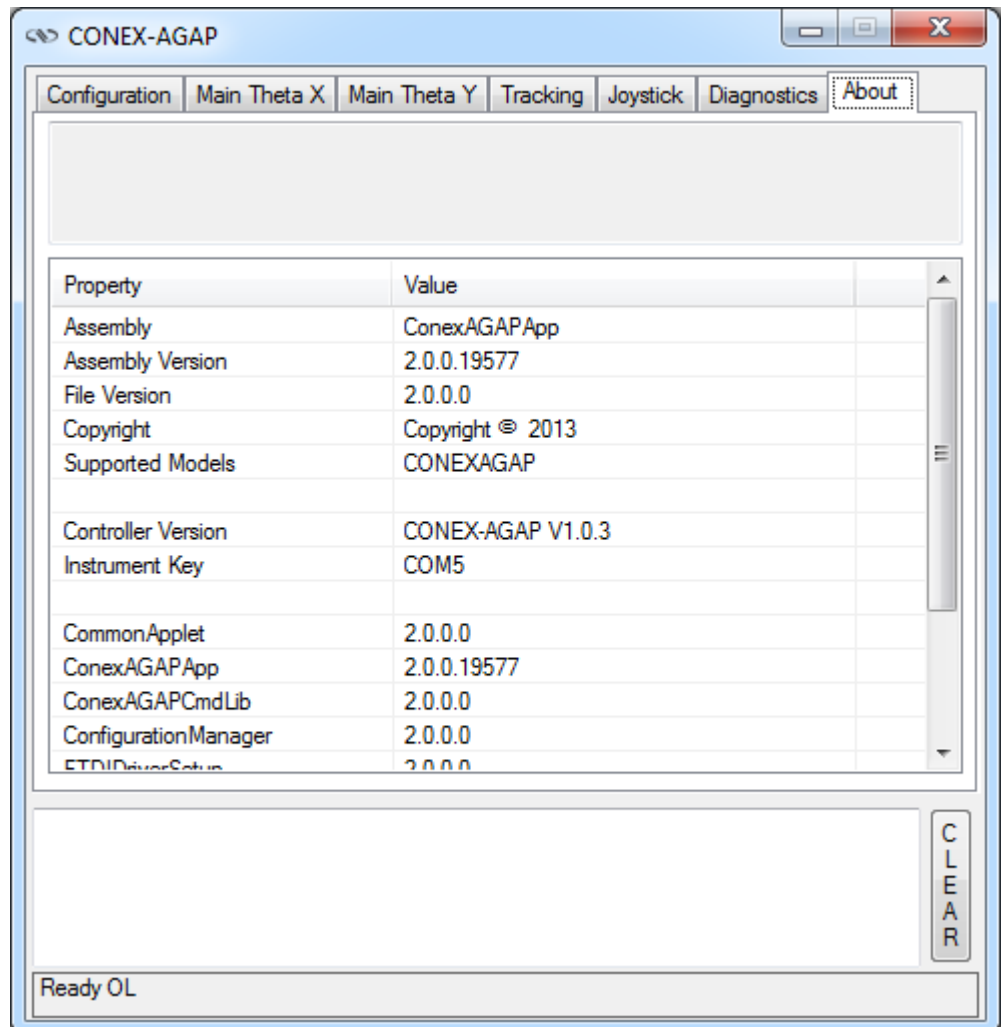
Service Form

Name: _____

Company:_____

Address: _____

Country: _____

P.O. Number: _____

Item(s) Being Returned:_____

Model#: _____

Return authorization #: _____
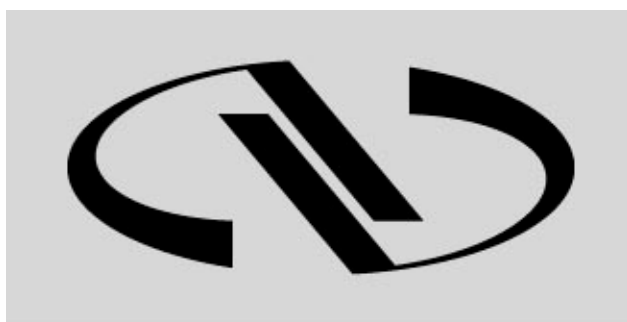
(Please obtain prior to return of item)

Date: _____

Phone Number: _____

Fax Number: _____

Serial #: _____

Description: _____

Reasons of return of goods (please list any specific problems): _____

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