## ILS SEries <br> High-Performance Mid-Range Travel Linear Stages <br> OीR2 | Newport"

## FEM-optimized Aluminum Body

The optimized aluminum body allows for extreme stiffness and minimizes bi-metal bending without compromising weight. The rigid body reduces deflection under load.

## Integrated Encoder

A $4000 \mathrm{pts} / \mathrm{rev}$. encoder is mounted directly on the screw in order to prevent screw/motor coupling errors consequently boosting stage motion accuracy. The HA version features an integrated linear scale with $0.3 \mu \mathrm{~m}$ MIM.


Need Higher Accuracy?
For critical positioning applications, Newport offers micropositioning calibration services. We will create, implement and verify an electronic compensation process to improve the absolute position accuracy of select ILS-HA Series stages when commanded by our XPS advanced motion control system. Compensation is performed at $20.0^{\circ} \mathrm{C}, \pm 0.2^{\circ} \mathrm{C}$, for linear and non-linear errors, ensuring accuracy of up to $1 \mu \mathrm{~m}$ $+1 \mu \mathrm{~m} / 100 \mathrm{~mm}$ over center $80 \%$ of travel. A certificate of calibration per Newport Metrology Procedure A167 and measured error maps are provided.


| Design Details |  |
| :---: | :---: |
| Base Material | Extruded Aluminum |
| Bearings | Double-row recirculating ball bearinsg |
| Drive Mechanism | Backlash-free ball screw |
| Drive Screw Pitch (mm) | 2 |
| Feedback | ILS-CC, ILS-CCL, ILS-BPP: <br> Screw mounted rotary encoder, 4,000 cts/rev, index pulse ILS-HA: Linear steel scale, $20 \mu \mathrm{~m}$ signal period, $0.1 \mu \mathrm{~m}$ resolution |
| Limit Switches | Optical |
| Origin | Optical, at center of travel, including mechanical zero signal |
| Cable | 3 m long cable include |

## Metrology Report

## Included at No Additional Cost

Newport guarantees specification values which are measured and recorded following ASME B5.57 and ISO 230-2 standards. The typical performance values are two times better than the guaranteed specifications.

## Other Features

A rigid top cover prevents damage to the drive train and protects it from dust and debris. ILS Series stages also feature an origin located at the center of travel for repeatable initialization, limit switches to prevent over travel, and elastomeric end-of-run dampers for smooth emergency braking.

## Load Characteristics and Stiffness



| Cz, | Normal centered load capacity | 250 N |
| :--- | :--- | :---: |
| $-\mathrm{Cx},+\mathrm{Cx}$, | Axial load capacity | $<40 \mathrm{~N}$ |
| $K \alpha x$, | Compliance in roll | $15 \mu \mathrm{rad} / \mathrm{Nm}$ |
| $K \alpha y$, | Compliance in pitch | $10 \mu \mathrm{rad} / \mathrm{Nm}$ |
| $\mathrm{K} \mathrm{\alpha z}$, | Compliance in yaw | $10 \mu \mathrm{rad} / \mathrm{Nm}$ |
| O, | Off-center load (N) | $0 \leq \mathrm{Cz} \div(1+\mathrm{D} / 60)$ |
|  | Where $\mathrm{D}=$ Cantilever distance $(\mathrm{mm})$ |  |

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## Specifications

|  | ILS-BPP, ILS-CC, ILSCCL (1) | ILS-HA |
| :---: | :---: | :---: |
| Travel Range (mm) | 50, 100, 150, 200 and 250 |  |
| Minimum Incremental Motion ( $\mu \mathrm{m}$ ) | 1.0 | 0.3 |
| Uni-directional Repeatability, Typical (Guaranteed) ( $\mu \mathrm{m}$ ) | 1.0 | 0.4 |
| Bi-directional Repeatability, Typical (Guaranteed) ${ }^{(2)}(\mu \mathrm{m})$ |  |  |
| ILS50 | \pm 0.40 ( $\pm 1.0)$ | $\pm 0.10( \pm 0.35)$ |
| ILS100 | $\pm 0.40( \pm 1.0)$ | $\pm 0.10( \pm 0.35)$ |
| ILS150 | \pm 0.45 ( $\pm 1.0)$ | $\pm 0.15( \pm 0.35)$ |
| ILS200 | \pm 0.45 ( $\pm 1.0)$ | $\pm 0.15( \pm 0.35)$ |
| ILS250 | $\pm 0.60( \pm 1.0)$ | $\pm 0.15( \pm 0.35)$ |
| Accuracy CC, BPP \& CCL, Typical (Guaranteed) ${ }^{(2)}(\mu \mathrm{m})$ |  |  |
| ILS50 | $\pm 0.6( \pm 1.5)$ | $\pm 0.3( \pm 1.25)$ |
| ILS100 | $\pm 0.8( \pm 2.0)$ | \pm 0.6 ( $\pm 1.5)$ |
| ILS150 | $\pm 1.5( \pm 2.5)$ | $\pm 1.2( \pm 2.0)$ |
| ILS200 | $\pm 1.2( \pm 3.7)$ | $\pm 0.8( \pm 3.0)$ |
| ILS250 | $\pm 1.7( \pm 5.0)$ | $\pm 1.5( \pm 3.75)$ |
| Maximum Speed (mm/s) | $\begin{aligned} & \text { ILS-BPP, ILS-CCL: } 50 \\ & \text { ILS-CC: } 100 \end{aligned}$ | 100 |
| Pitch, Typical (Guaranteed) ${ }^{(2)(3)}$ ( $\mu \mathrm{rad}$ ) |  |  |
| ILS50 | $\pm 15$ ( $\pm 25$ ) | $\pm 17( \pm 25)$ |
| ILS100 | $\pm 20$ ( $\pm 50$ ) | $\pm 25$ ( $\pm 50$ ) |
| ILS150 | $\pm 37( \pm 75)$ | $\pm 50$ ( $\pm 75$ ) |
| ILS200 | $\pm 37( \pm 100)$ | $\pm 35( \pm 100)$ |
| ILS250 | $\pm 42( \pm 125)$ | $\pm 45( \pm 125)$ |
| Yaw, Typical (Guaranteed) ${ }^{(2)(3)}$ ( $\mu \mathrm{rad}$ ) |  |  |
| ILS50 | $\pm 12( \pm 25)$ | $\pm 7( \pm 25)$ |
| ILS100 | $\pm 17( \pm 37)$ | $\pm 17( \pm 37)$ |
| ILS150 | $\pm 20$ ( $\pm 65$ ) | $\pm 25$ ( $\pm 65$ ) |
| ILS200 | $\pm 25$ ( $\pm 80$ ) | $\pm 25( \pm 80)$ |
| ILS250 | $\pm 25$ ( $\pm 95$ ) | $\pm 30$ ( $\pm 95$ ) |
| MTBF (h) 20,000 | 20,000 |  |

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## Dimensional Drawing

(M-)ILS


| MODEL (METRIC) | A | n1 | B | C | n2 | L2 | VERSIONS CC, CCL AND PP |  | VERSION CCHA |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  |  |  | L1 | L3 | L1 | L3 |
| (M-)ILS50 | - | 2 | - | 5.0 (127) | 2 | 8 (203) | 14 (358) | 4.8 (123) | 15.5 (394) | 6.3 (159) |
| (M-)ILS100 | - | 2 | - | 3.0 (76.2) | 2 | 10 (253) | 16 (408) | 4.8 (123) | 17.5 (444) | 6.3 (159) |
| (M-)ILS150 | - | 2 | 3.0 (76.2) | 3.0 (76.2) | 4 | 12 (303) | 18 (458) | 4.8 (123) | 19.4 (494) | 6.3 (159) |
| (M-)ILS200 | 3.94 (100) | 4 | 3.0 (76.2) | 3.0 (76.2) | 4 | 14 (353) | 20 (508) | 4.8 (123) | 21.4 (544) | 6.3 (159) |
| (M-)ILS250 | 3.94 (100) | 4 | 3.0 (76.2) | 3.0 (76.2) | 4 | 16 (403) | 22 (558) | 4.8 (123) | 23.4 (594) | 6.3 (159) |

## Top Plate



MODEL SHOWN: M-ILS \& M-ILS-LM INTERFACE


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## Ordering Information

| Model | Series | Travel (mm) | Drive |  |
| :---: | :---: | :---: | :---: | :---: |
| M- | ILS | $\left[\begin{array}{c} 50 \\ 100 \\ 150 \\ 200 \\ 250 \end{array}\right]$ | $-\left[\begin{array}{c} \mathrm{CC} \\ \mathrm{CCL} \\ \mathrm{HA} \\ \mathrm{BPP} \end{array}\right.$ | Example: <br> The ILS150HA is an ILS stage with 150 mm travel, a DC motor drive with linear encoder, in English version. |

M-: $\quad$ For metric version
CC: DC motor
CCL: DC motor for SMC100CC controller
HA: DC motor with linear encoder
BPP: Stepper motor

## Recommended Controllers / Drivers

| Model Number | 1- to 8-axis universal <br> high-performance motion <br> controller/driver |
| :---: | :--- |
| XPS-Dx | 1 Universal digital driver <br> card for stepper, DC and <br> direct motors |
| XPS-DRV11 | 1- to 4-axis universal <br> high-performance motion <br> controller/driver |
| XPS-RLDx | 1- to 3-axis motion control- <br> ler/driver |
| ESP302-xN | Single-axis DC motor <br> controller/driver |
| SMC100CC | Single-axis stepper motor <br> controller/driver |
| SMC100PP |  |



Two IMS stages, one ILS stage, and one EQ120bracket in an XYZ configuration.

Accessory Bracket Dimensional Drawing: EQ120


An RVS80 mounted in a vertical configuration with an EQ120 bracket to an ILS stage.

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[^0]:    1) ILS-CCL used with the SMC100CC controller only.
    2) Shown are peak to peak, guaranteed specifications or $\pm$ half the value as sometimes shown. For the definition of typical specifications which are about $2 X$ better than the guaranteed values, visit www.newport.com for the Motion Control Metrology Primer.
    3) To obtain arcsec units, divide $\mu$ rad value by 4.8.
